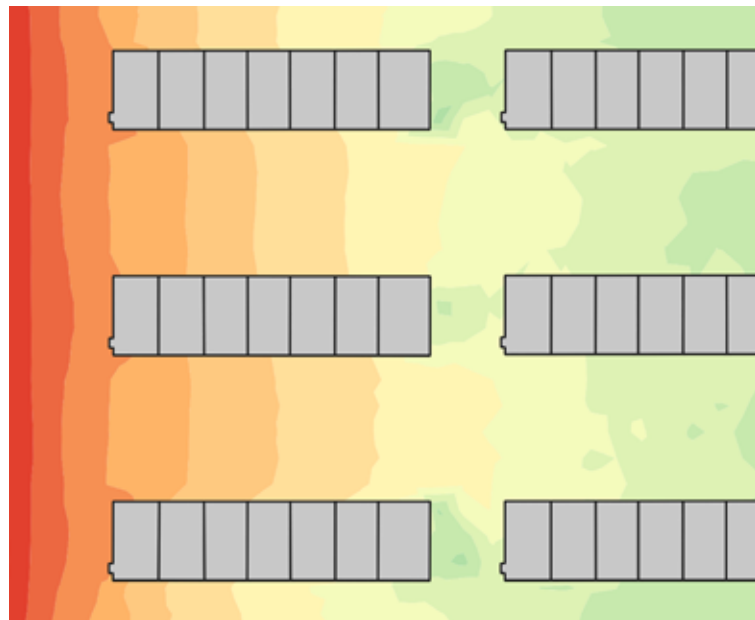
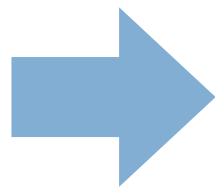


NADINE HOBEIKA  
CONSTANTIJN DINKLO  
DENIS GIANNELLI  
LAURENS VAN RIJSSEL  
MAARIT PRUSTI

JANTIEN STOTER  
BALÁZS DUKAI

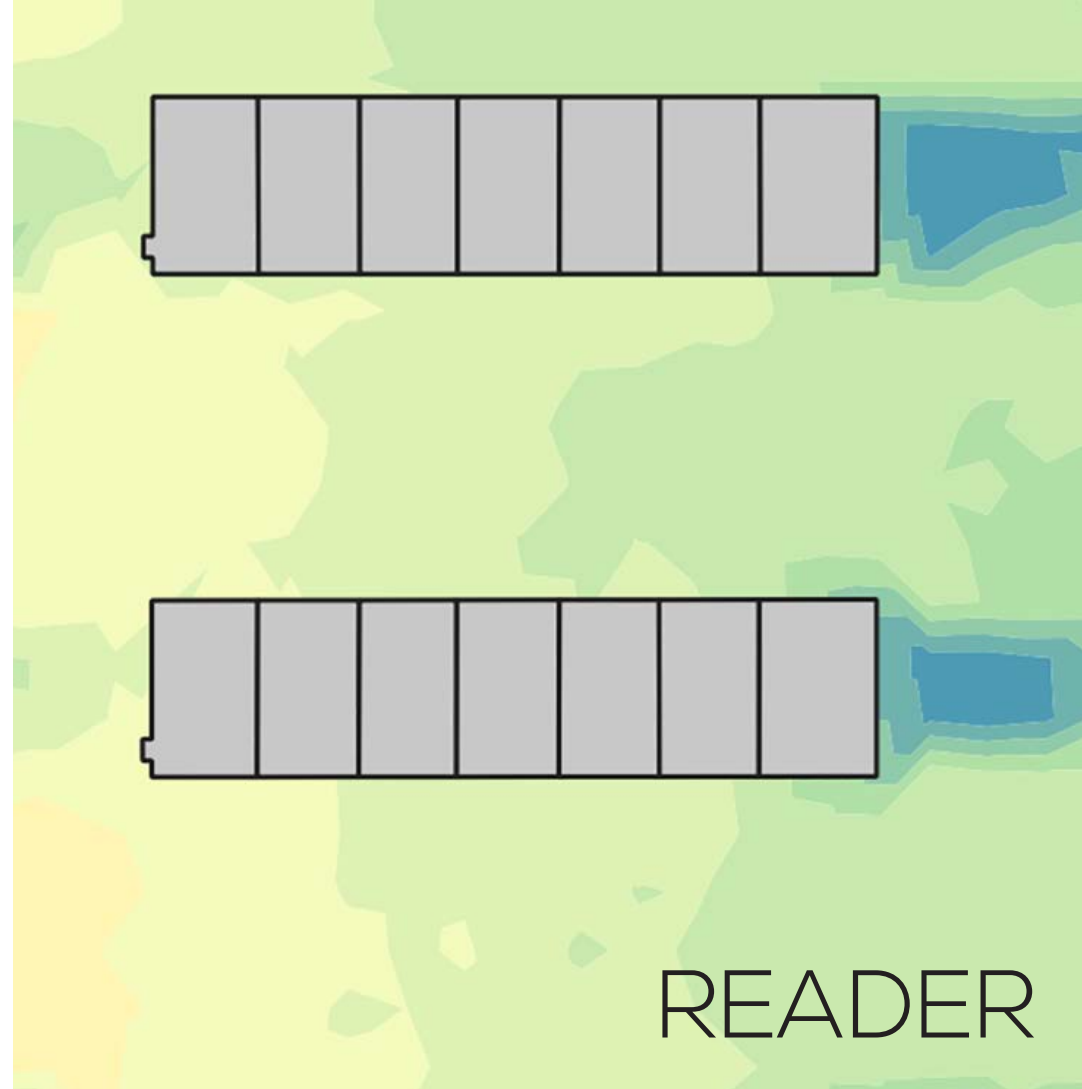
ARNAUD KOK  
RENEZ NOTA  
ROB VAN LOON

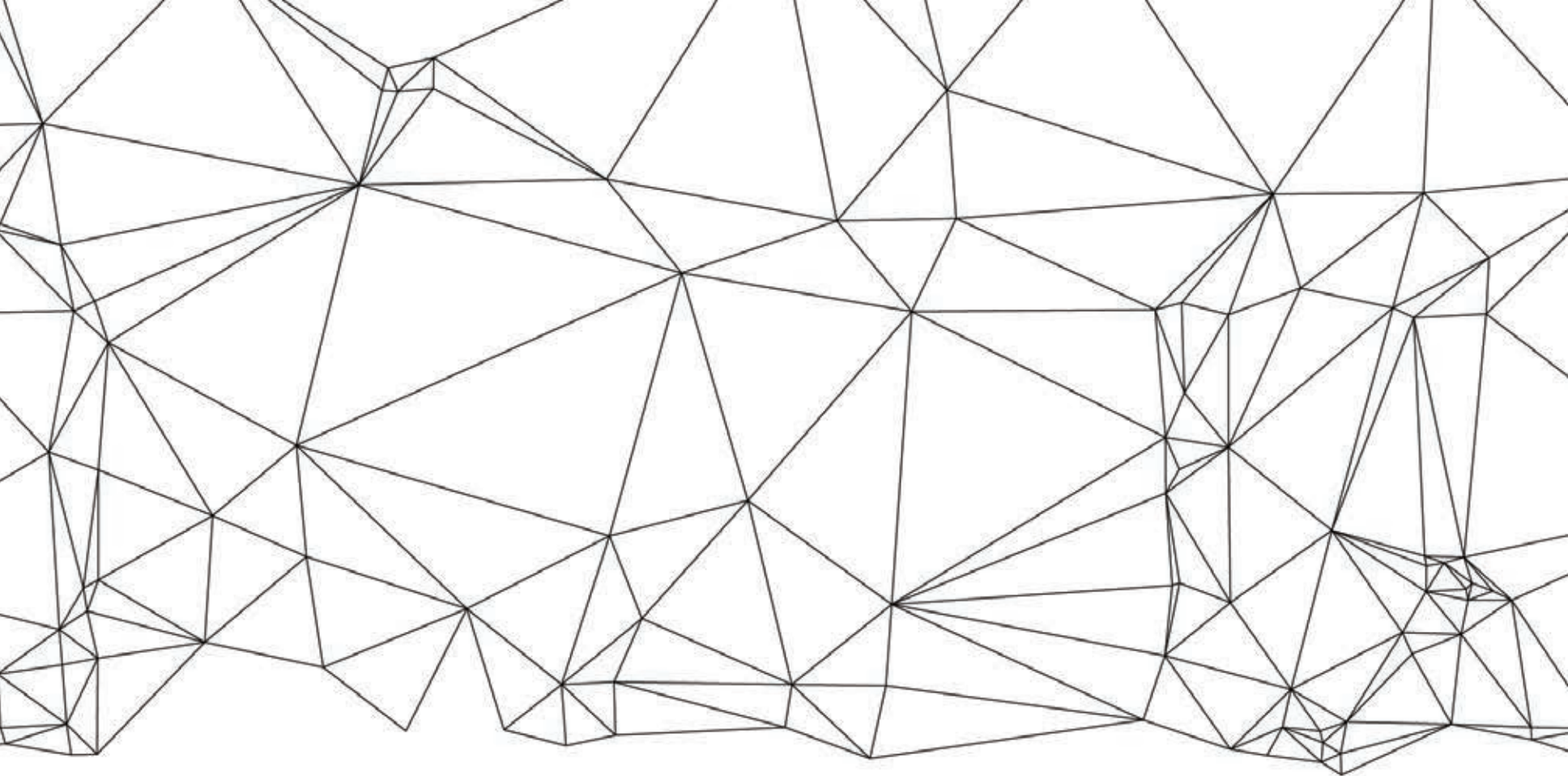
**3D NOISE SIMULATION**



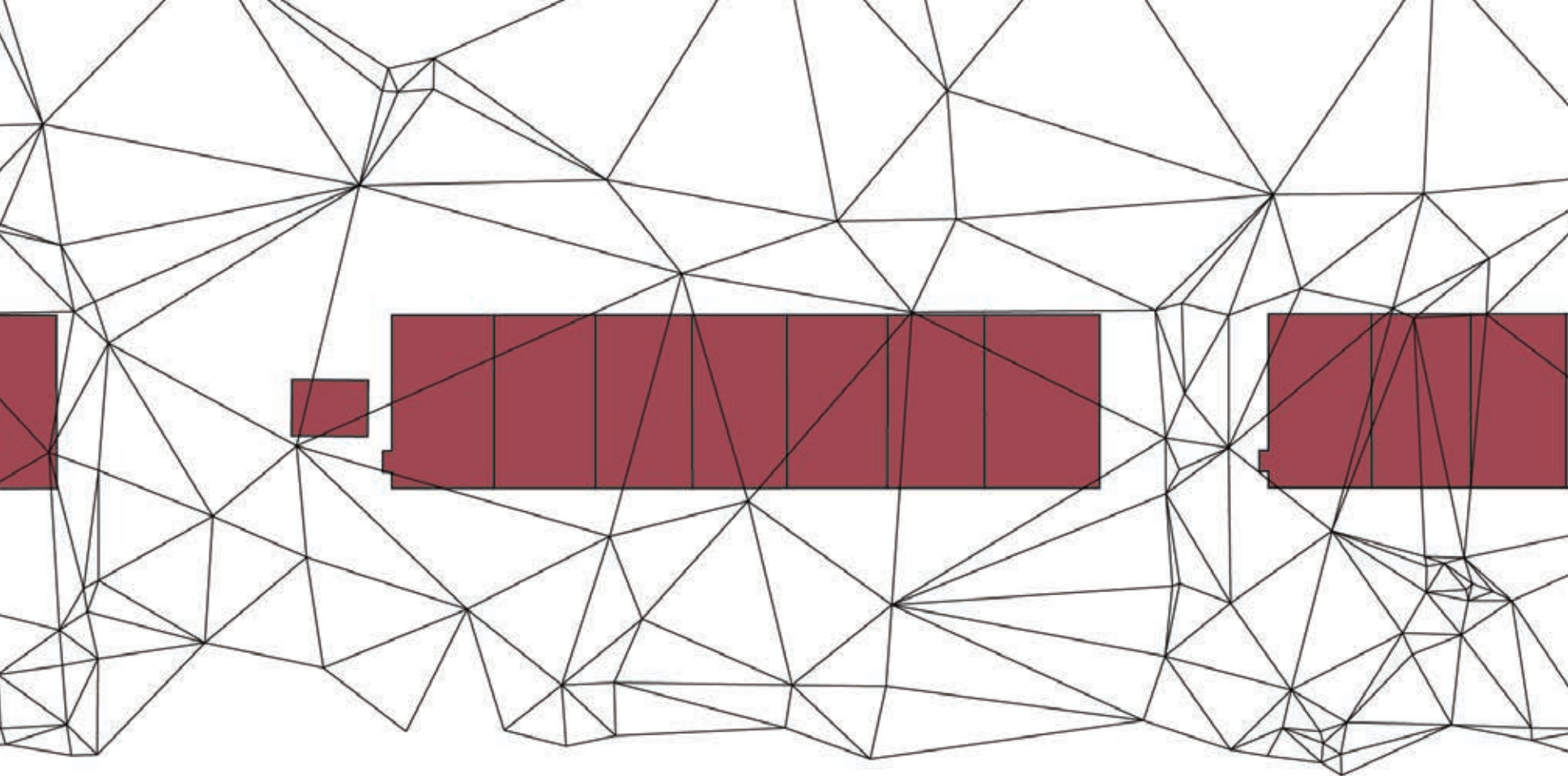
OBJECTIVE

- ALGORITHM
- RESULTS
- QUALITY
- LIMITATIONS
- CONCLUSION

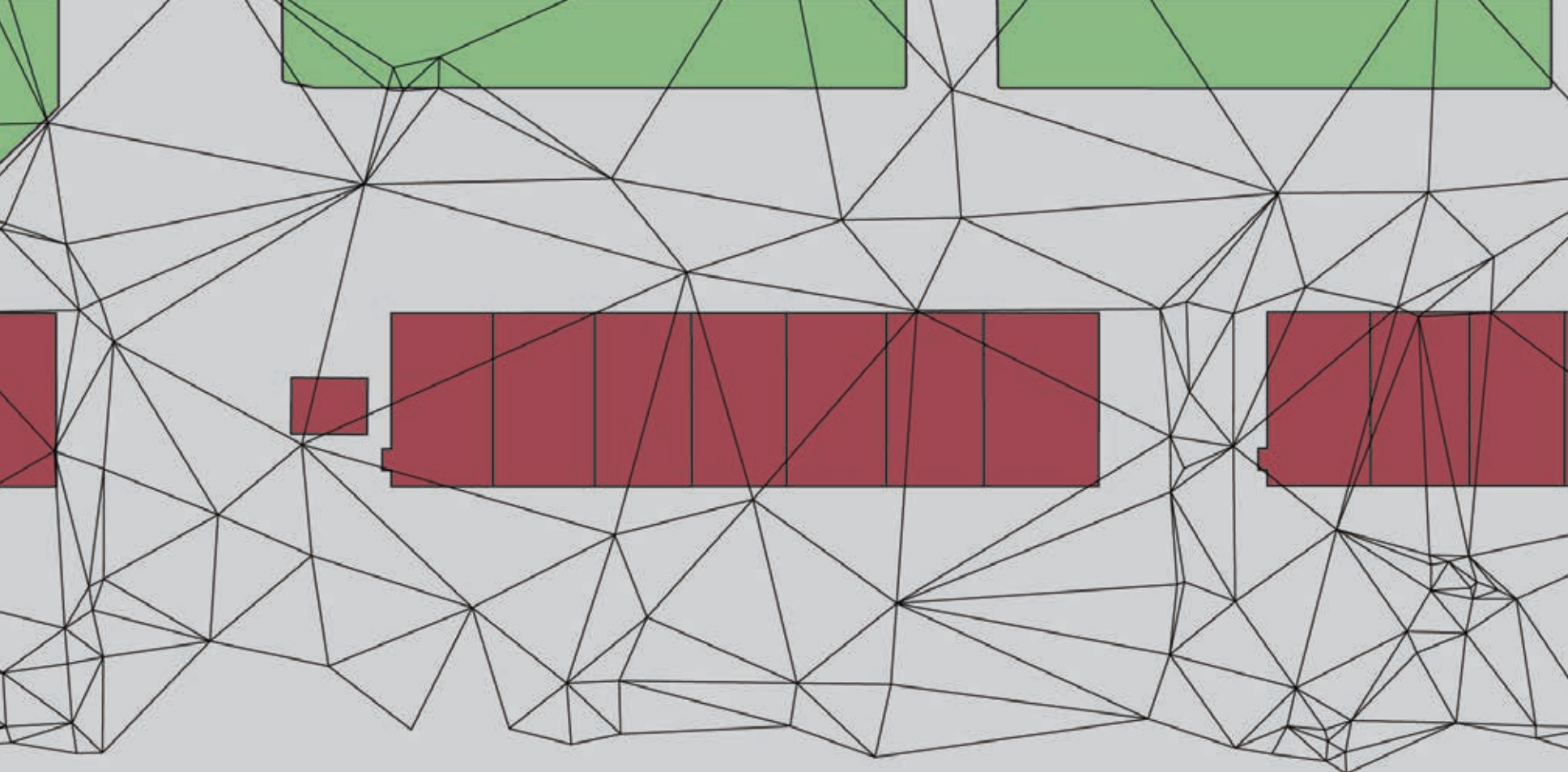




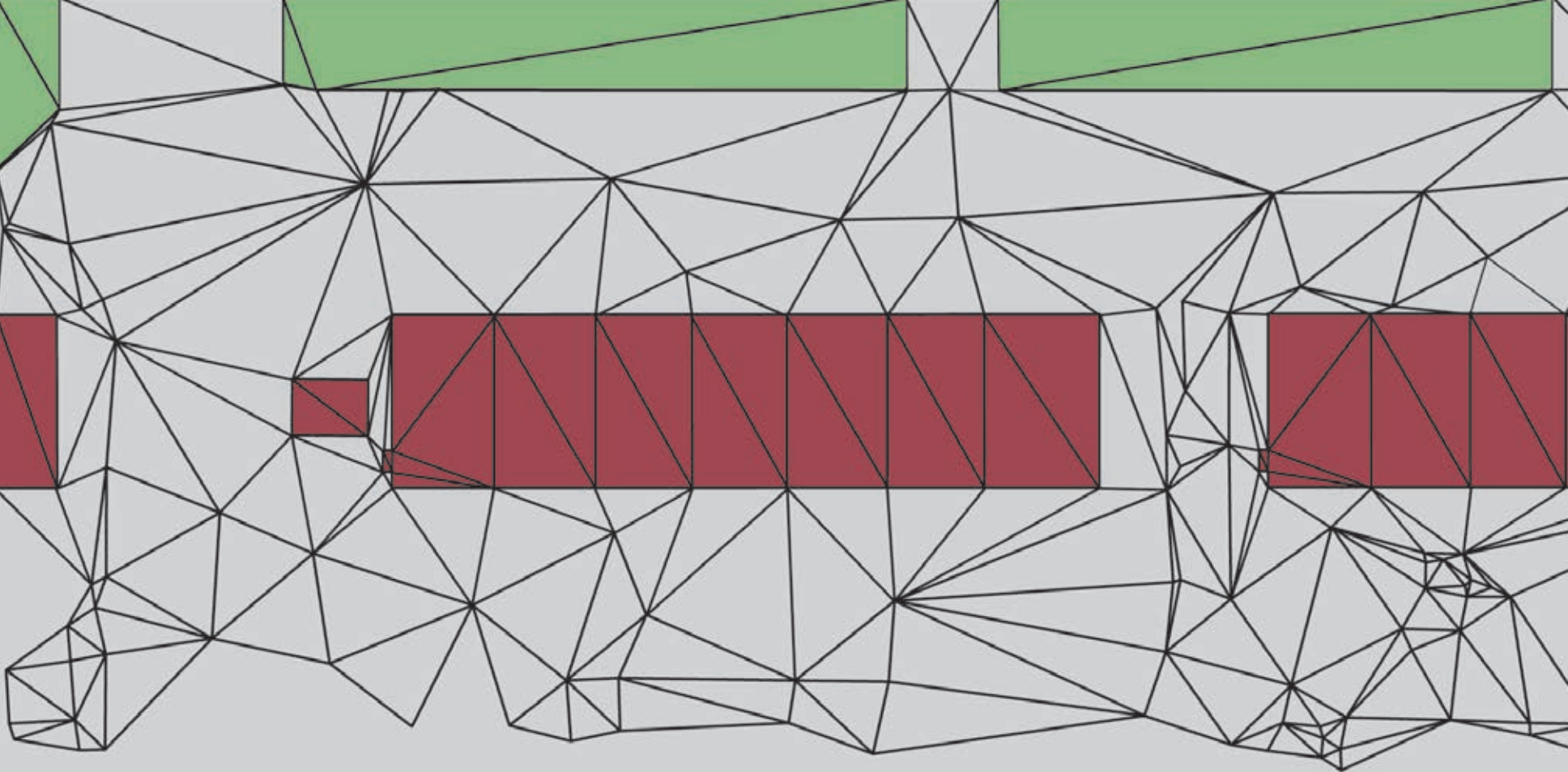
GROUND TIN



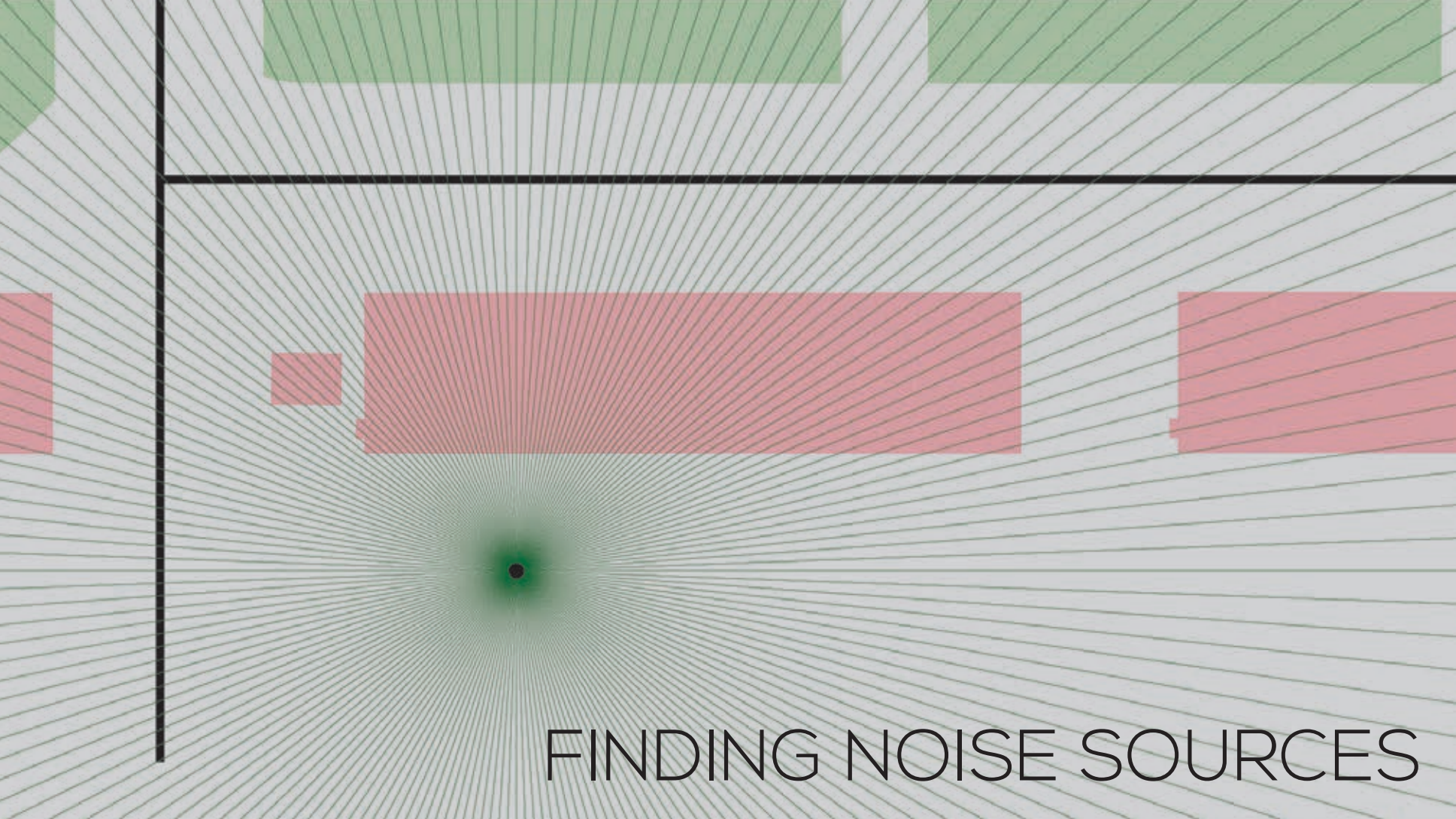
BUILDINGS



GROUND TYPES

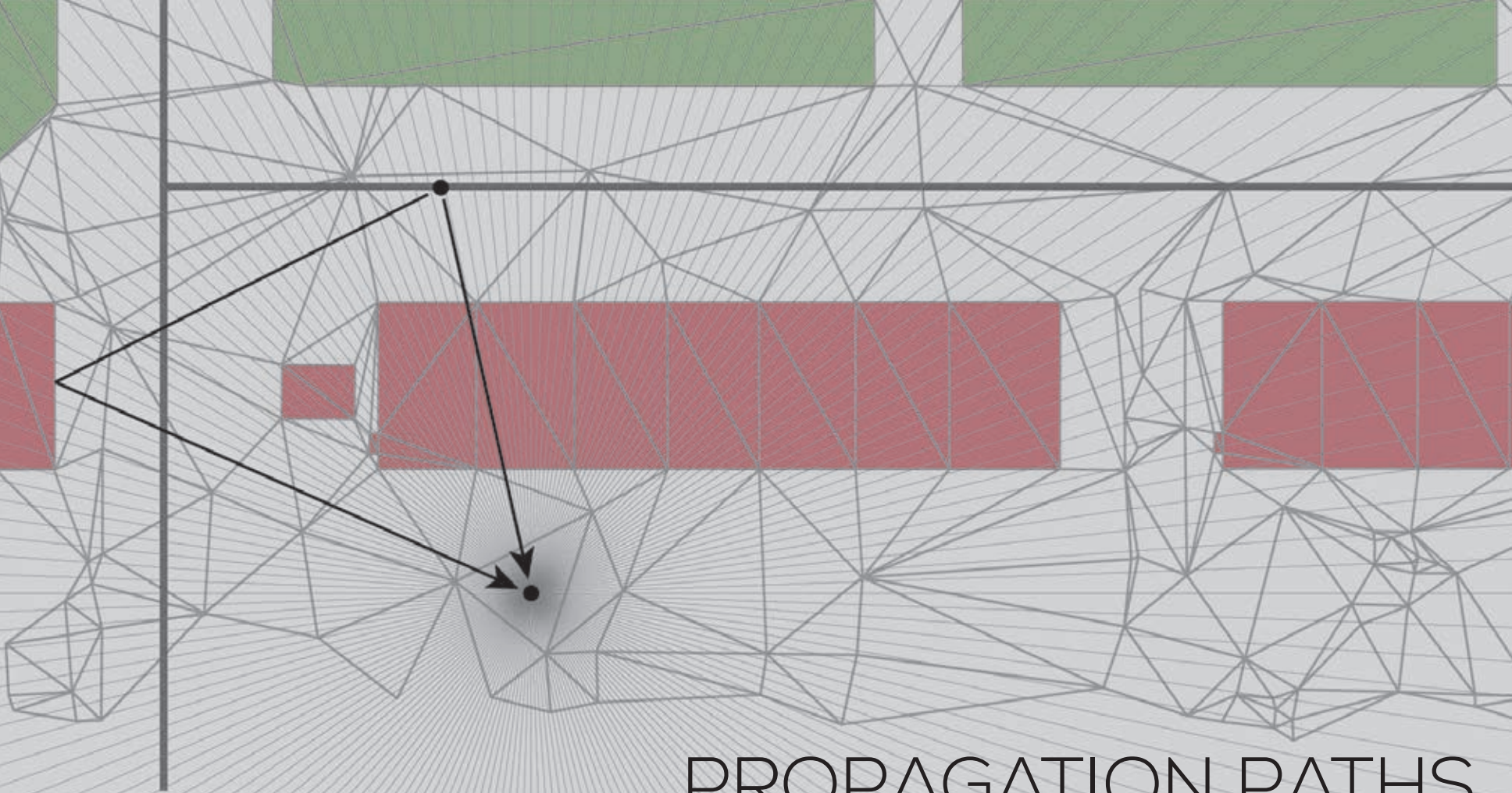


CONSTRAINED TIN

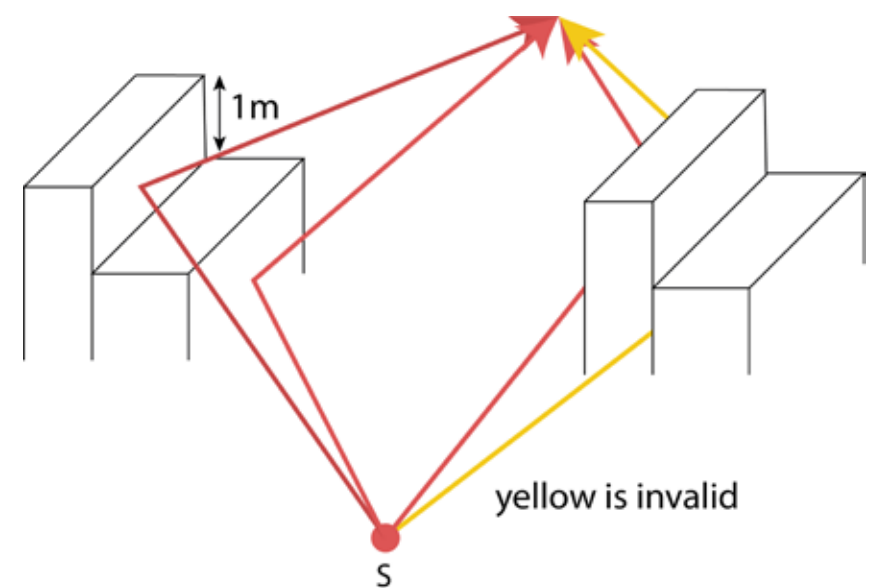
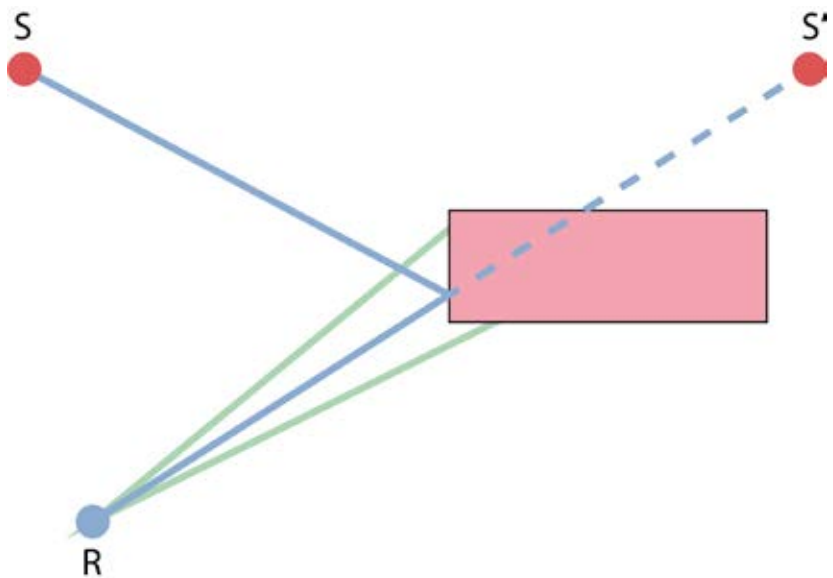


FINDING NOISE SOURCES

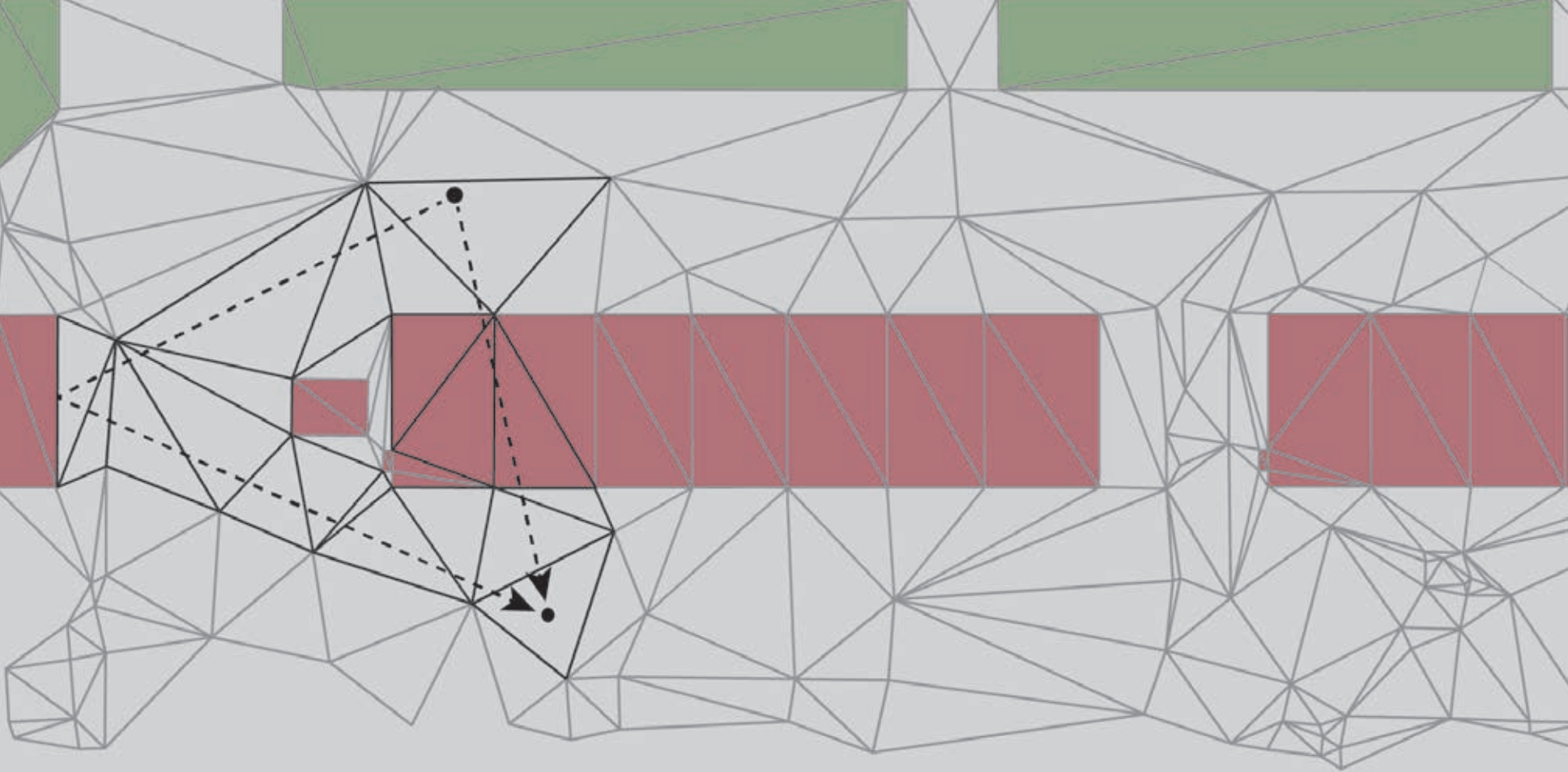




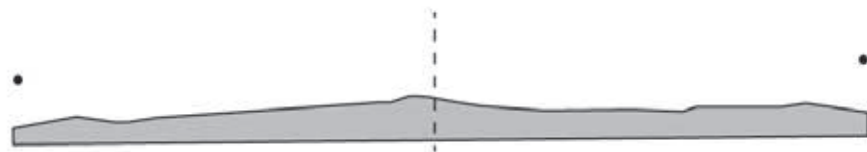
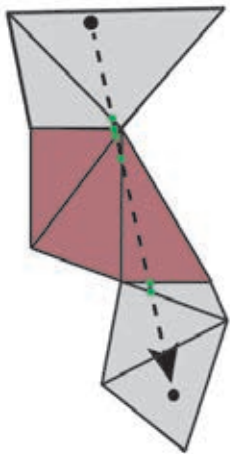
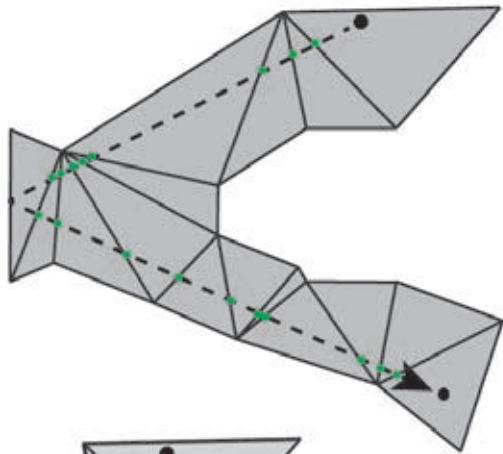
PROPAGATION PATHS



# TESTS FOR REFLECTED PATHS



WALKING ALGORITHM

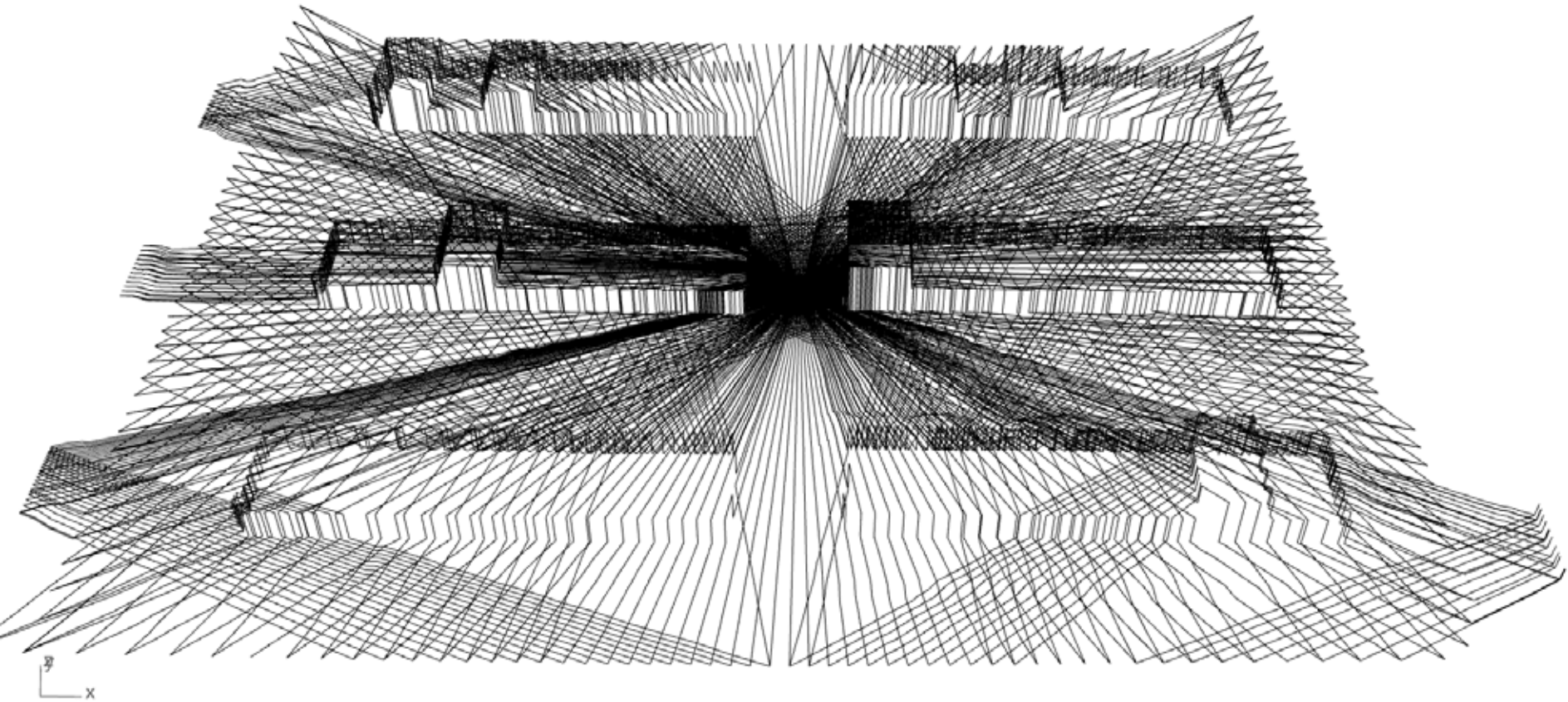


REFLECTED PATH

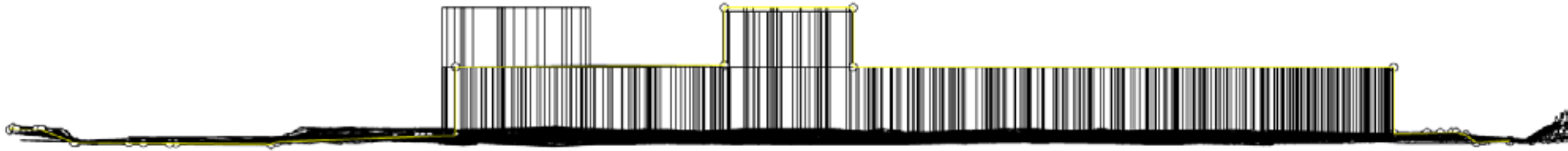


DIRECT PATH

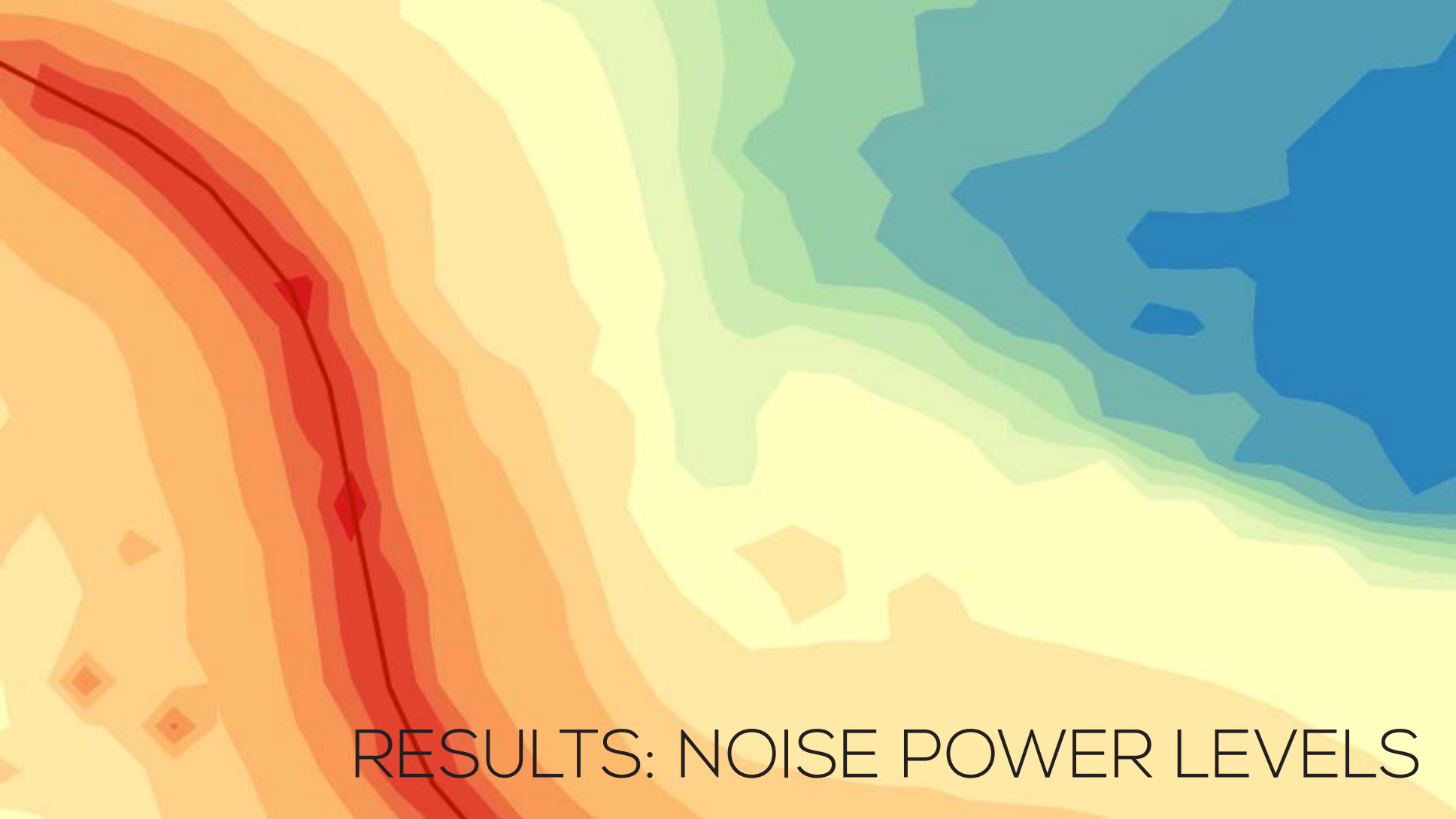
CROSS-SECTIONS FROM WALKING



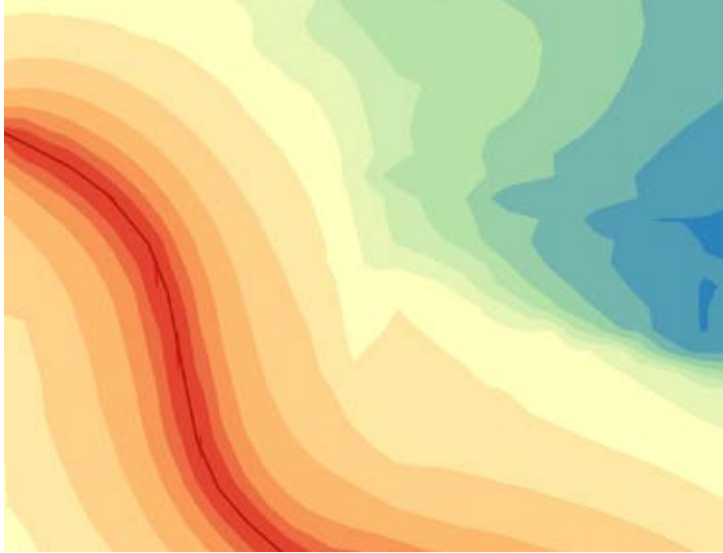
RESULTS: CROSS-SECTIONS



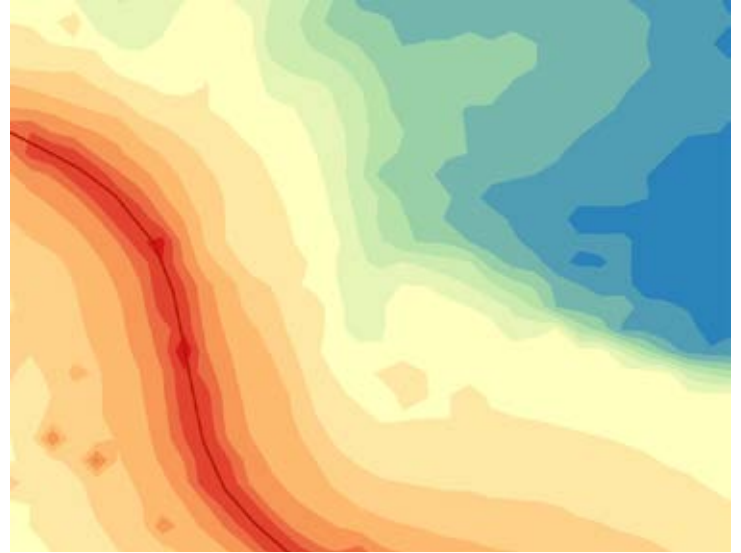
RESULTS: CROSS-SECTIONS



RESULTS: NOISE POWER LEVELS



NOISE RESULTS BY RIVM

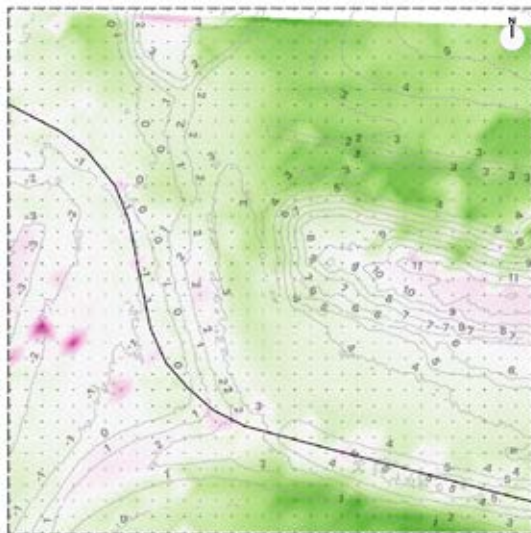


NOISE RESULTS BY US

QUALITY: SCENARIO WITHOUT REFLECTIONS

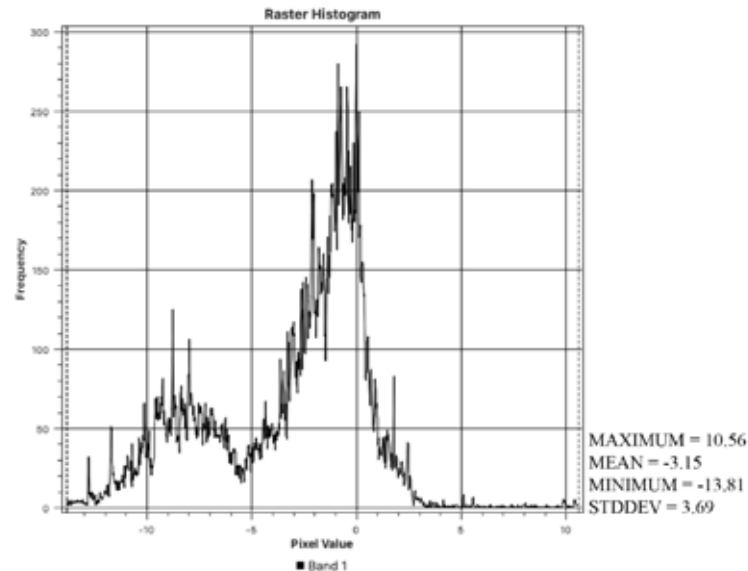


SCENARIO 2 - NOISE POWER LEVEL DIFFERENCE (%)



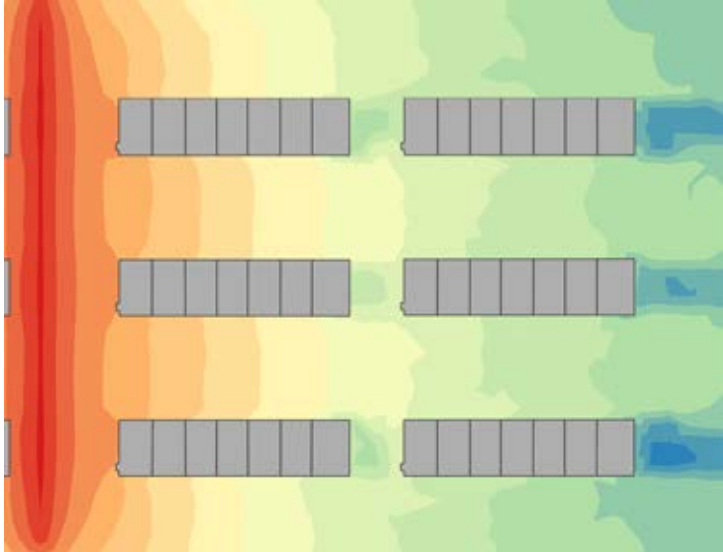
NOISE RESULTS BY RIVM

SCENARIO 4 - NOISE POWER LEVEL DIFFERENCE (%)

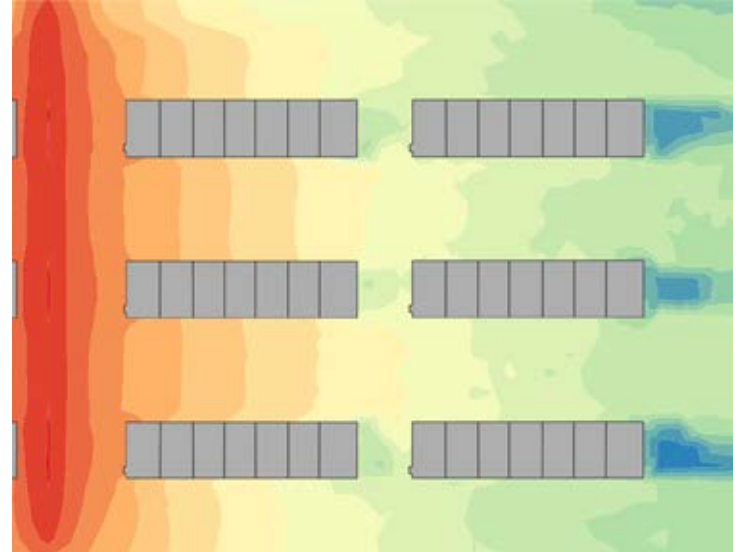


NOISE RESULTS BY US

QUALITY: SCENARIO WITHOUT REFLECTIONS



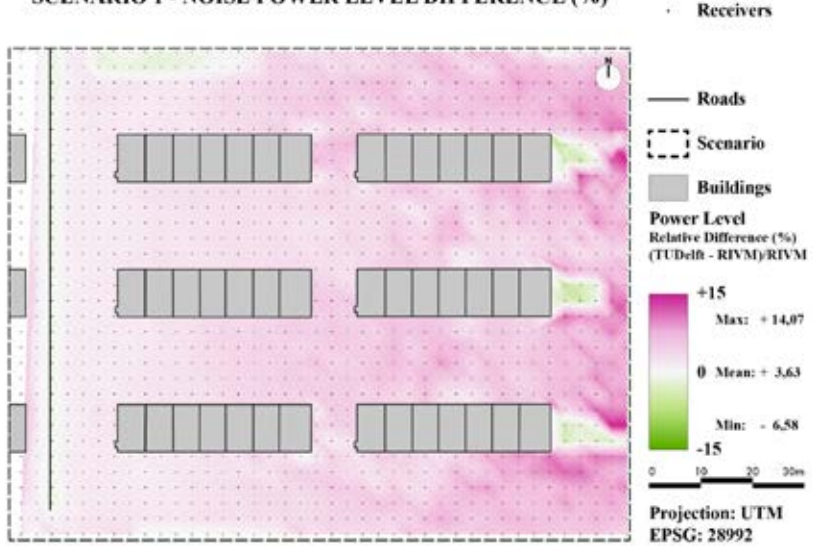
NOISE RESULTS BY RIVM



NOISE RESULTS BY US

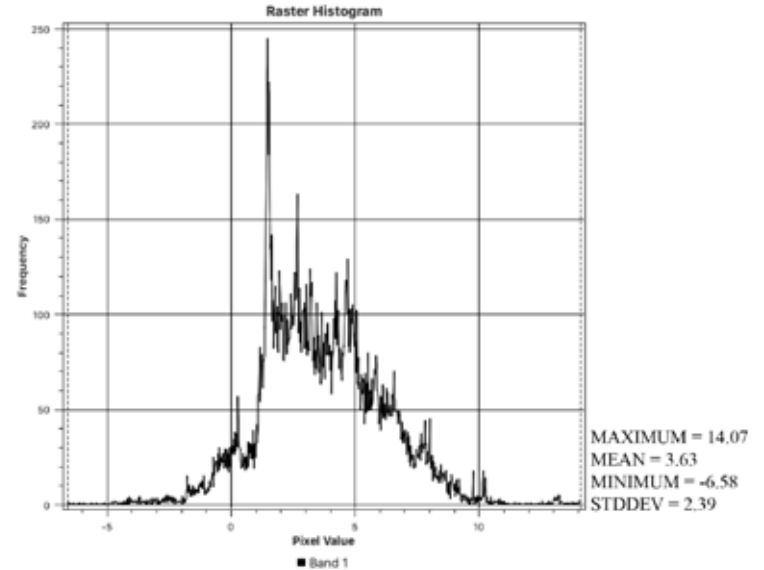
QUALITY: SCENARIO WITH REFLECTIONS

SCENARIO 1 - NOISE POWER LEVEL DIFFERENCE (%)



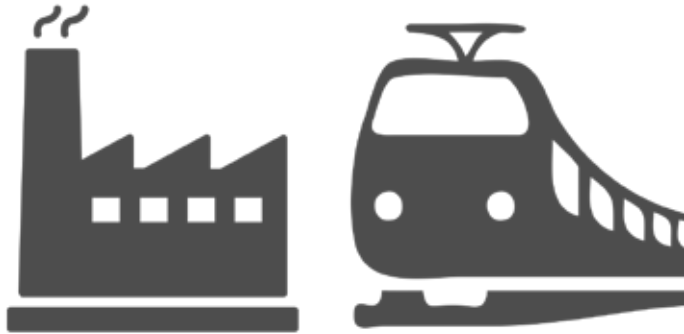
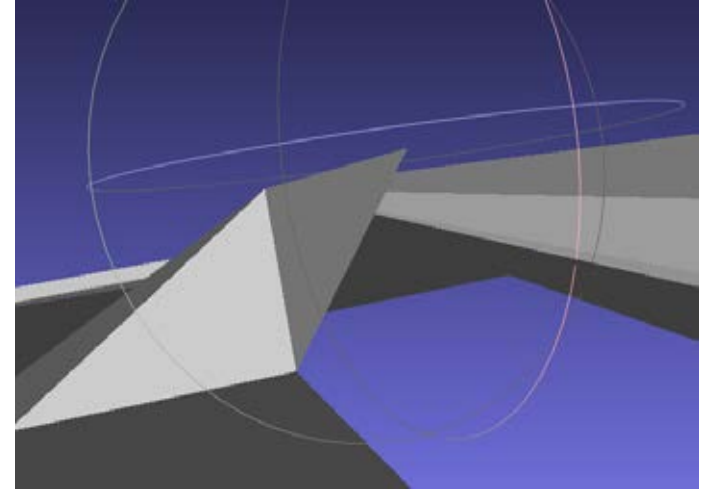
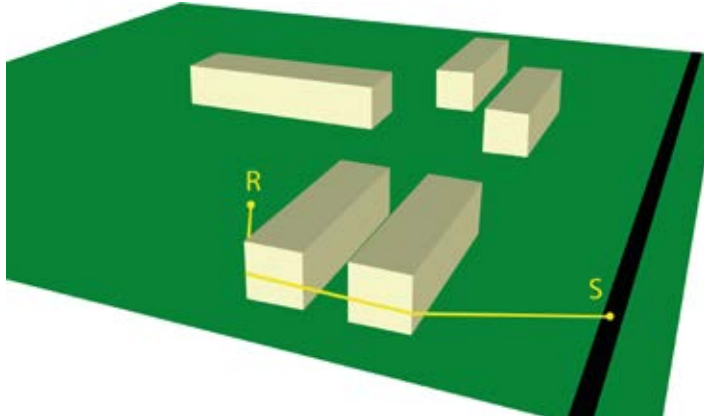
NOISE RESULTS BY RIVM

SCENARIO 1 - NOISE POWER LEVEL DIFFERENCE (%)

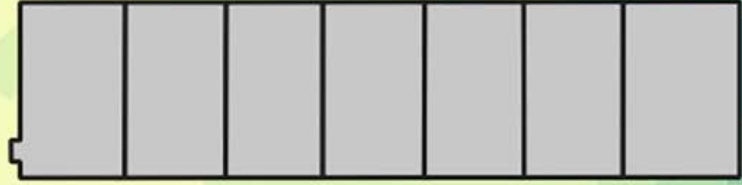
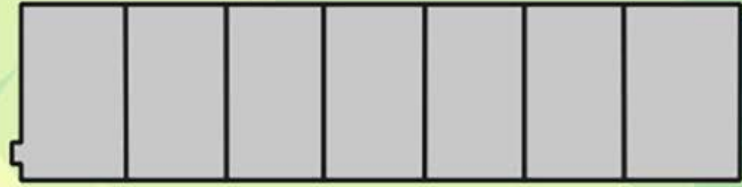
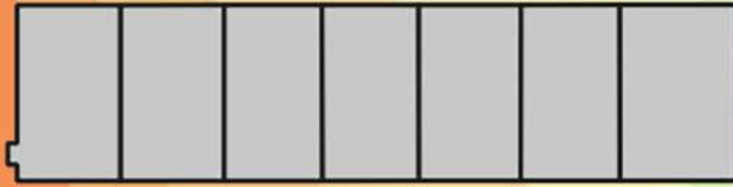


NOISE RESULTS BY US

QUALITY: SCENARIO WITH REFLECTIONS



LIMITATIONS



CONCLUSION AND FURTHER RESEARCH