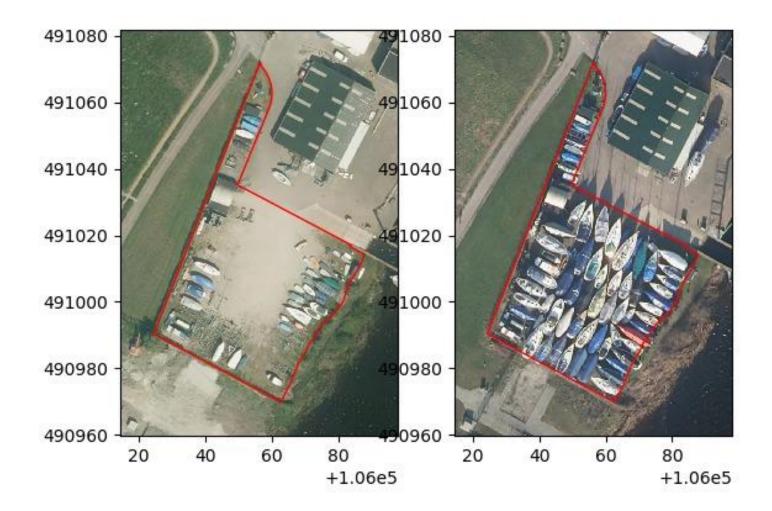
Automatic change detection in digital maps using aerial images and point clouds

Felix Dahle

Mentor #1: Ken Arroyo Ohori Mentor #2: Giorgio Agugiaro Mentor #3: Sven Briels

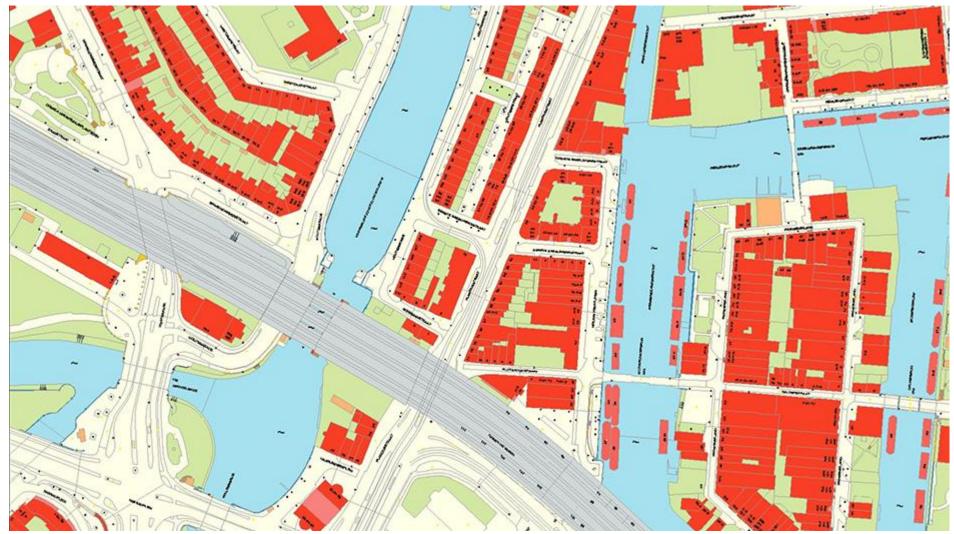








# Digital maps must be updated regulary – still done by hand







#### Content

- 1. Introduction
- 2. Related work & Background
- 3. Methodology
- 4. Implementation
- 5. Results
- 6. Discussion



### Introduction



### **Motivation**



- Susceptible for errors
- Time consuming



### Solution is machine learning

Machine Learning can support this process through automization of the change detection

#### Input

- Aerial images & point clouds from consecutive years
- Digital map from current year

#### Output

- Which polygons are changing (probability per polygon)
- Support of the manual updating process

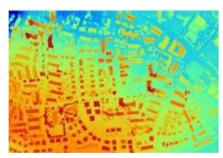


# Data from various sources is used for one research area

#### Input data



Aerial images



Point cloud (DSM)



**Digital maps** 

#### **Research area**

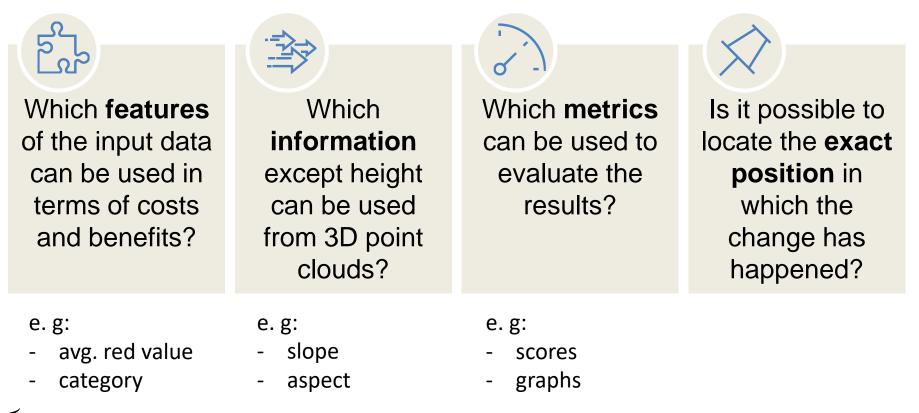






### **Research questions**

To what extent can the change detection be automated using machine learning algorithms?





# Related work & Background



### Insights from related research

Change detection used for many applications with **different techniques**: pixel-based  $\rightarrow$  object-based  $\rightarrow$  height included  $\rightarrow$  machine learning

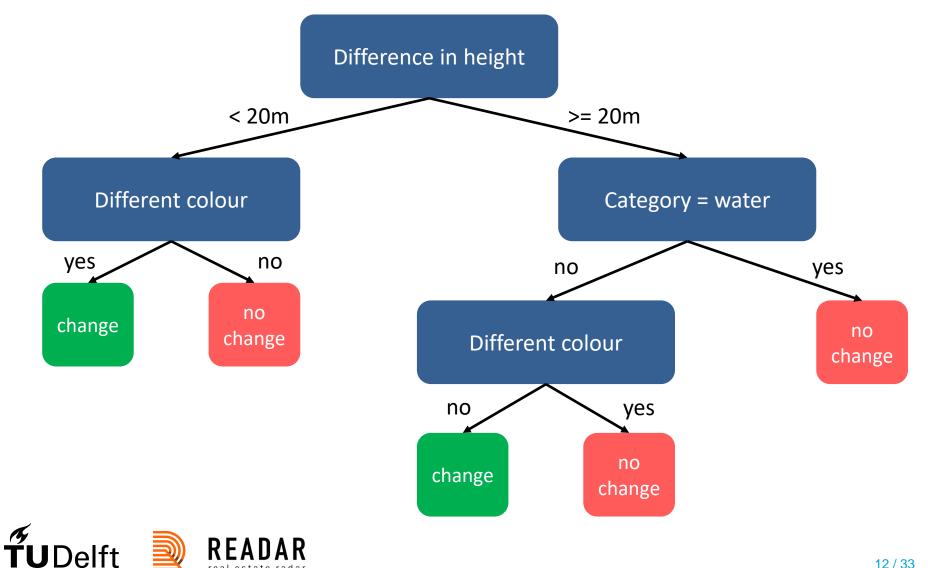


Holistic approaches are rare

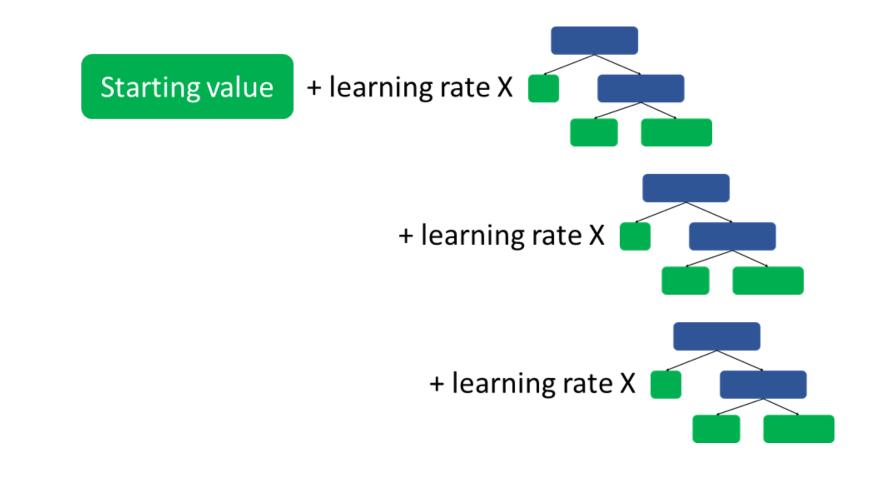
For ML deep learning is used in most cases, **XGBoost is used less** 



### Decision trees help to classify based on many weak features

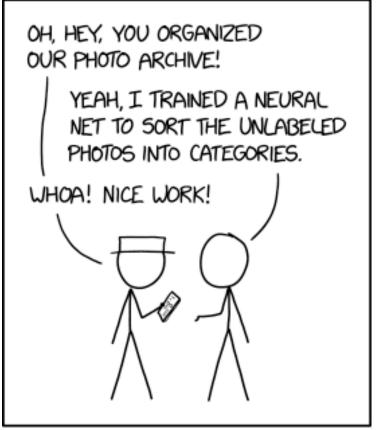


# Gradient boosting combines multiple decision trees





### Machine learning in a nutshell



ENGINEERING TIP: WHEN YOU DO A TASK BY HAND, YOU CAN TECHNICALLY SAY YOU TRAINED A NEURAL NET TO DO IT.

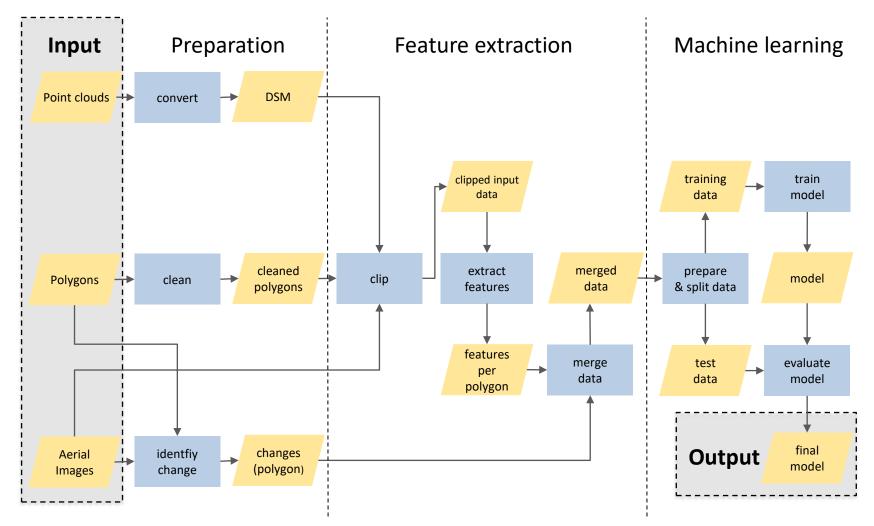




# Methodology



# Workflow can be divided in three big parts





READAR



# Features from different categories are used as input for XGBoost

#### **Colour features**

• Statistical values for RGB & HSV

#### **Height features**

- Statistical values for height & aspect & slope
- Number of pixels close to median height

#### **Polygon features**

- Category
- Shape of the polygon

#### **Progressive features**

Shadow

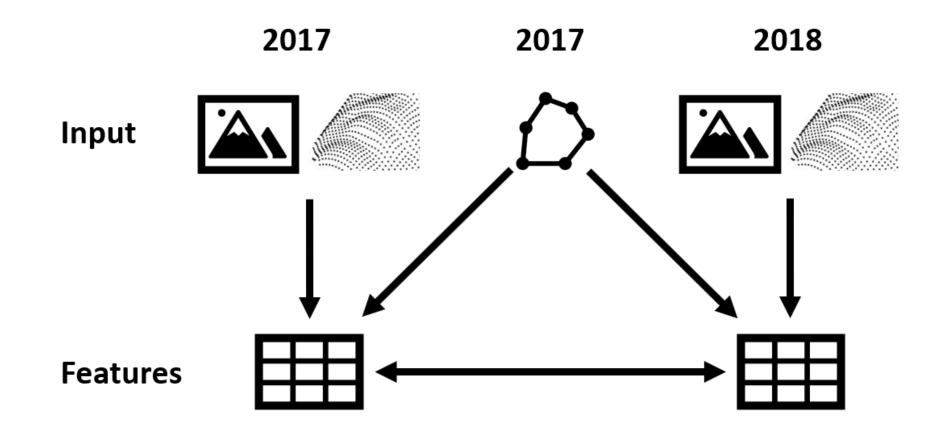
Haralick

Local binary patterns

Bhattacharyya
Fourier



# Features for both years are based on the polygons from 2017





# Implementation

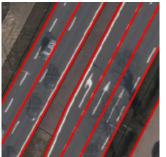


# For multiple BGT classes change detection is applied





Wegdeel





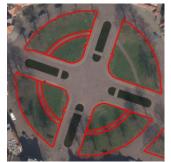
Gebouwinstallatie

Overigbouwwerk



Waterdeel





Begroeidterreindeel



Onbegroeidterreindeel



Ondersteunendwaterdeel



Ondersteunendwegdeel





### Features consist of numerical information

| 45 - | +4.873 | Be5 |    |            | 1           |
|------|--------|-----|----|------------|-------------|
| 40 - |        |     |    |            |             |
| 35 - | and    |     |    | 1          |             |
| 30 - |        | 15  |    |            |             |
| 25 - | -      | in  |    |            | The second  |
|      | 50     | 55  | 60 | 65<br>+1.0 | 70<br>946e5 |

| Colour Features          |              | Height Features       |              | Polygon Features                  |              | Progressive Features   |              |
|--------------------------|--------------|-----------------------|--------------|-----------------------------------|--------------|--|--------------|
| Feature                  | <u>Value</u> | Feature               | <u>Value</u> | <u>Feature</u>                    | <u>Value</u> | <u>Feature</u>   | <u>Value</u> |
| red_min                  | 103          | height_<br>avg        | 29.774       | n_pixels                          | 630          | shadow_<br>percentage  | 7.04         |
| red_max                  | 154          | height_<br>first_perc | 24.252       | length_x                          | 6.4          | haralick_<br>contrast  | 167.902      |
| red_avg                  | 122.98       | height_<br>last_perc  | 31.579       | length_y                          | 3.5          | haralick_<br>Entropy   | 87.730       |
| red_first_<br>percentile | 106          | slope_avg             | 14.171       | compact<br>ness                   | 0.702        | Peaks  | 0.7880       |
| red_last_<br>percentile  | 143          | aspect                | 159.691      | n_vertices                        | 5            | LBP[1]**   | 0            |
| red_mode                 | 124          | npix_<br>height       | 0.825        | Category                          | Building*    | LBP[4]   | 7            |
| red_std                  | 8.63         |                       |              |                                   |              |  |              |
|                          |              | 1                     |              | *will be converted to a<br>number |              | ** the number corresponds<br>to the position at the<br>histogram |              |



# High number of objects with only a small percentage of changes





### Results

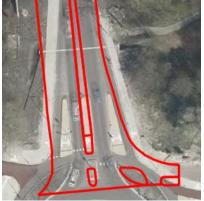


# Many changes could be classified correctly











**ŤU**Delft



### The outcome of my model





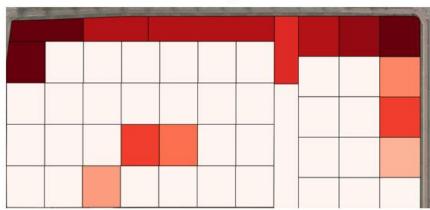
# Locate changes via splitting polygons is successful

2017





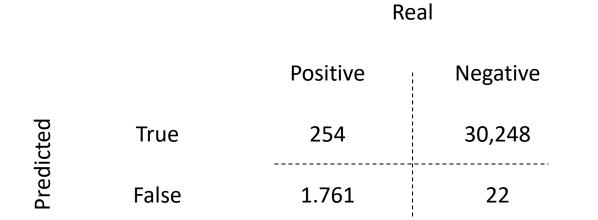
change







# Confusion Matrix can provide insights for the exact numbers

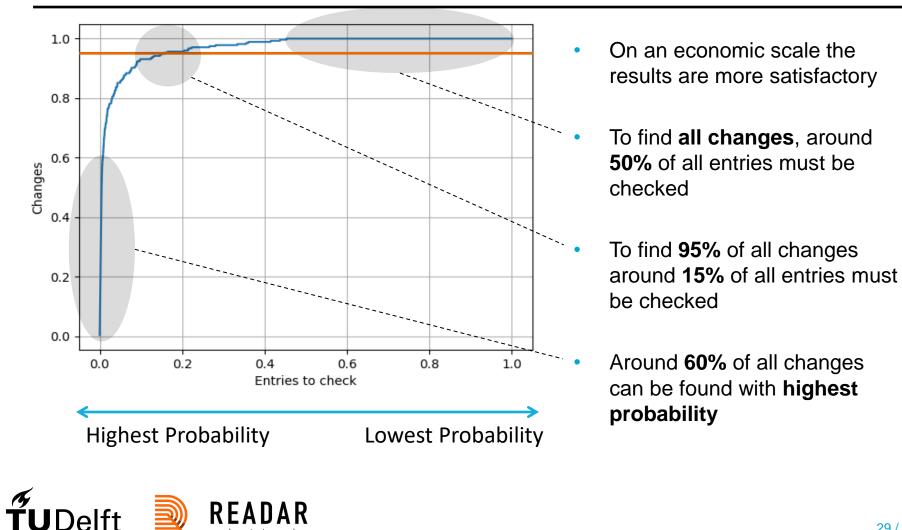


Size test-set: 32.385 Threshold = 0.001



# The economic curve displays the value for the customer

#### **Economic curve**



## Discussion



### Discussion

#### **Change detection**

- Best detection rate for buildings
- Mixed classes decrease detection rate
- More difficult for streets

#### Contributions

- Implemented a holistic change detection
- Used XGBoost for change detection

- Support for maintaining BGT
- Dealed with temporary changes

More training data needed

#### **Future research**

- Create features from deep learning
- Create a public test-set



# Research questions could be answered successfully

### To what extent can the change detection be automated using machine learning algorithms?

- Change detection is possible using XGBoost
- Suitable as a tool to set focus on certain areas
- Manual checking still required

